Software Installation:

The software is a windows based application. The software requires .Net4 Framework, Zigbee FT232R USB UART driver, Kinect Software and Camera Drivers.

**.Net Framework**: This is required for further development of the software. We assume that the further development will be done only in MICROSOFT VISUAL STUDIO’s environment and .Net Framework is required for this.

**ZigBee FT232R USB UART Driver**: The medium of communication with the bot is through a wireless modem called ZigBee. Hence the drivers for this hardware are needed.

**Kinect Software**: The project requires input from a Kinect or Xbox 360 device. The software which communicates with the Kinect or Xbox 360 device as well as gives us required inputs is called Kinect Software. Hence Kinect software is needed. The driver of Kinect comes along with the Kinect Software.

**Camera Devices drivers**: The project has a camera system. Hence all the drivers required for the camera normal functionality are required for this software.